Cromwell's principle idealized under the theory of large deviations

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Cromwell's principle

- Cromwell's principle: P(model is wrong) > 0, i.e., the prior probability that the assumptions are incorrect is greater than 0—D. Lindley (2013), Understanding Uncertainty
 - Relevance to Bayesian model checking: Diagnostics often reveal that prior distributions require revision—impossible under Bayes's theorem if P(model) = 1
- Idealized Cromwell's principle: P(model) vanishes
 - Large deviations version of the infinitesimal probability due to A. Hájek and M. Smithson (2012), Synthese 187, 33–48

D. R. Bickel (2018), Statistics, http://bit.ly/2vkE23Q

Empirical distribution converges to max. entropy

$$p^{x}(\mu_{0}) = \operatorname{Prob}_{\bar{X}^{\operatorname{prior}} \sim \operatorname{N}(\mu_{0}, \sigma^{2}/n + \sigma_{0}^{2})} \left(\left(\bar{X}^{\operatorname{prior}} - \mu_{0} \right)^{2} \ge (\bar{x} - \mu_{0})^{2} \right)$$

$$\Gamma(\alpha; x) = \operatorname{clco} \left\{ \operatorname{N} \left(\mu_{0}, \sigma_{0}^{2} \right) : p^{x}(\mu_{0}) \ge \alpha, \mu_{0} \in \mathbb{R} \right\}$$

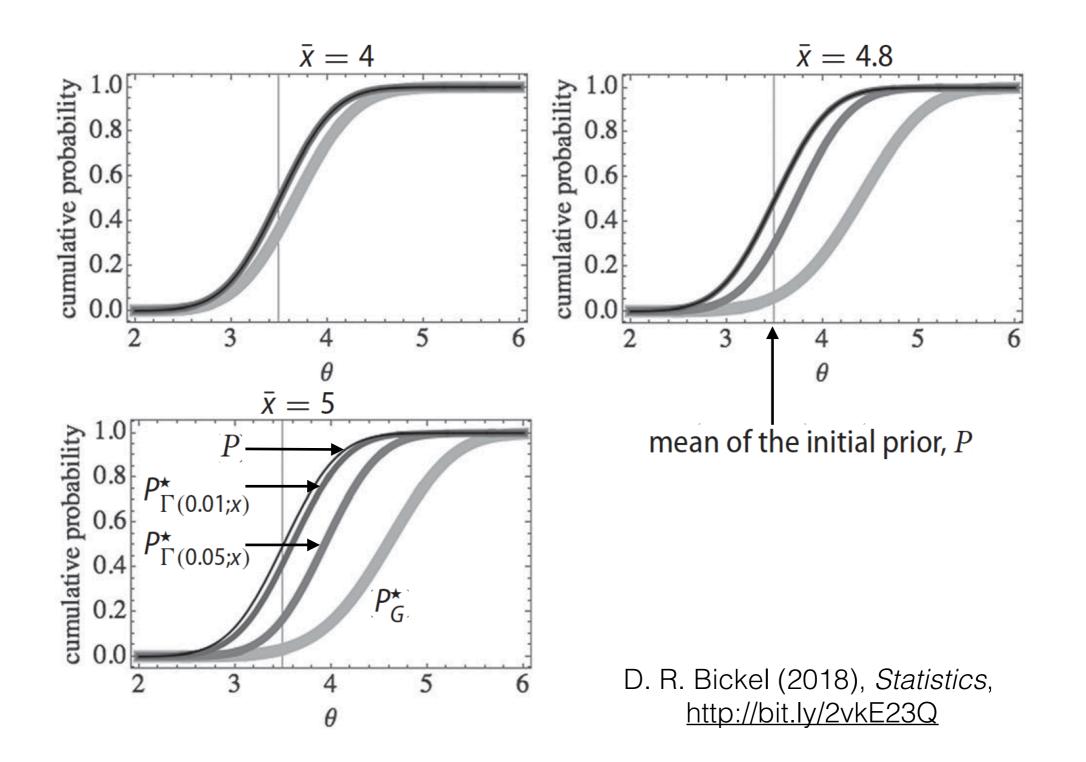
$$\inf_{P' \in \Gamma} D\left(P' || P \right) = \inf_{P' \in \operatorname{int} \Gamma} D\left(P' || P \right) < \infty$$

Weak convergence to maximum entropy distribution

$$D\left(P_{\Gamma}^{\star}||P\right) = \inf_{P' \in \Gamma} D\left(P'||P\right)$$

D. R. Bickel (2018), Statistics, http://bit.ly/2vkE23Q

Normal-normal CDFs



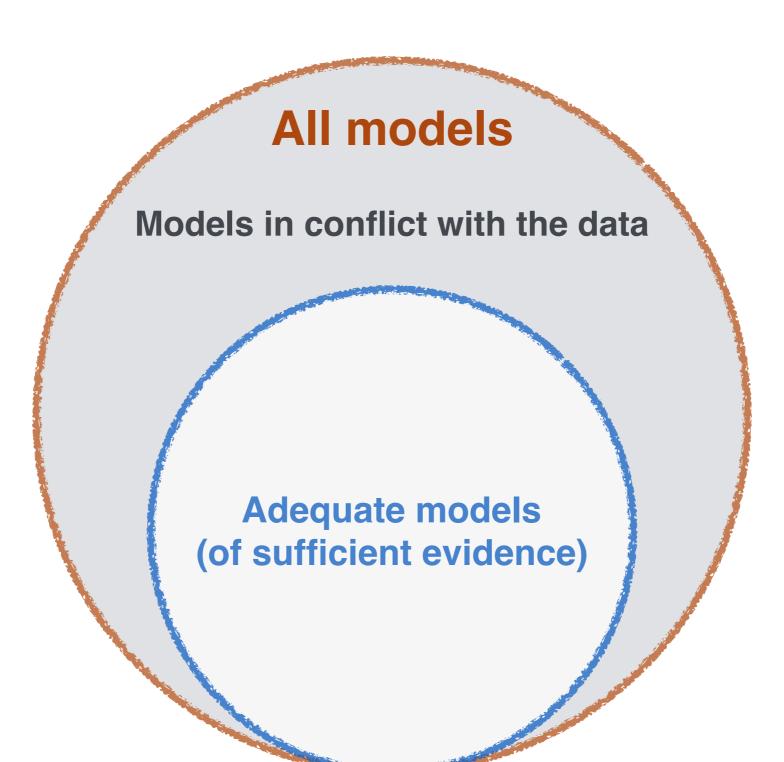
Adequate models have sufficient evidence

$$B\left(M;x\right) = \frac{f_M\left(x\right)}{f_{\neg M}\left(x\right)} = \frac{\int f_M\left(x|\theta\right)\pi_M\left(\theta\right)d\theta}{\int f_M\left(x|\theta\right)\pi_{\neg M}\left(\theta\right)d\theta}$$

$$w(M) = \log B(M; x)$$

$$\mathcal{M}(a) = \{ M \in \mathcal{M} : w(M) > a \}$$

Assessing multiple models



Bayesian model assessment

Does the prior or parametric family conflict with the data?

- Yes, if it has relatively low evidence
- Measures of evidence satisfying the criteria of Bickel, International Statistical Review 81, 188-206:
 - Likelihood ratio (limited to comparing two simple models)
 - Bayes factor
 - Penalized likelihood ratio



Use the model for decisions

(minimize posterior expected loss) even if other models are adequate

Change the model

to an adequate model, a model of high evidence

Loss function example

$$\ell\left(\theta,\delta\right) = \begin{cases} 0 & \text{if } \delta = \theta \in \{0,1\} \\ \ell_{\text{I}} & \text{if } \delta = 1, \theta = 0 \\ \ell_{\text{II}} & \text{if } \delta = 0, \theta = 1 \end{cases}$$

What act is appropriate?

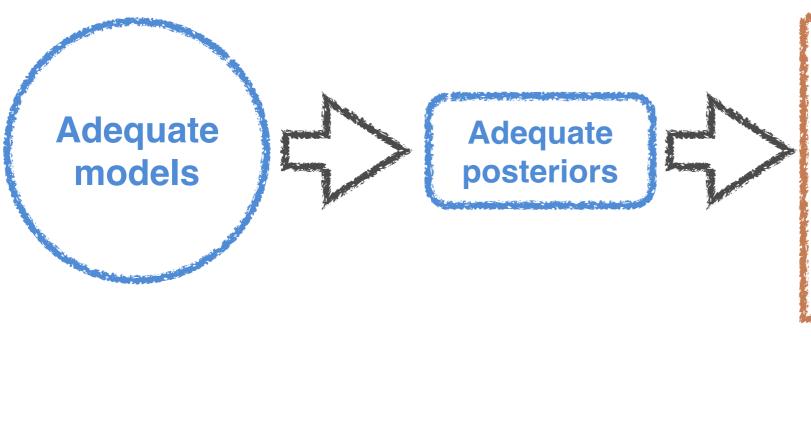
- Given multiple priors of sufficient evidence, agreement with the data
- With or without confidence sets

Hurwicz criterion

$$\delta\left(a,\kappa\right) = \arg\inf_{\delta\in\mathcal{D}} \left(\kappa \sup_{M\in\mathcal{M}(a)} E_M\left(\ell\left(\vartheta,\delta\right)\right) + (1-\kappa) \inf_{M\in\mathcal{M}(a)} E_M\left(\ell\left(\vartheta,\delta\right)\right)\right)$$

$$\ell(\theta, \delta) = \begin{cases} 0 & \text{if } \delta = \theta \in \{0, 1\} \\ \ell_{I} & \text{if } \delta = 1, \theta = 0 \\ \ell_{II} & \text{if } \delta = 0, \theta = 1 \end{cases}$$

$$\mathcal{M}(a) = \{ M \in \mathcal{M} : w(M) > a \}$$



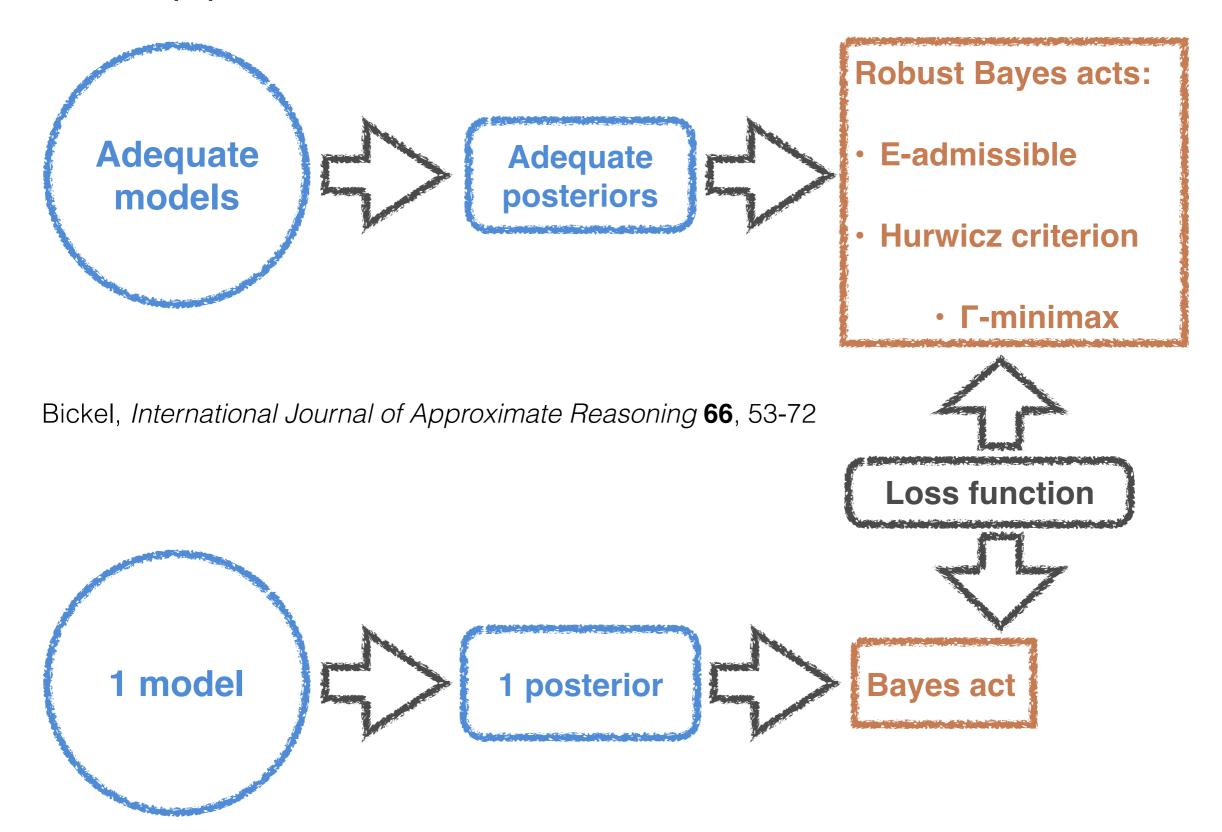
Robust Bayes act:

Hurwicz criterion

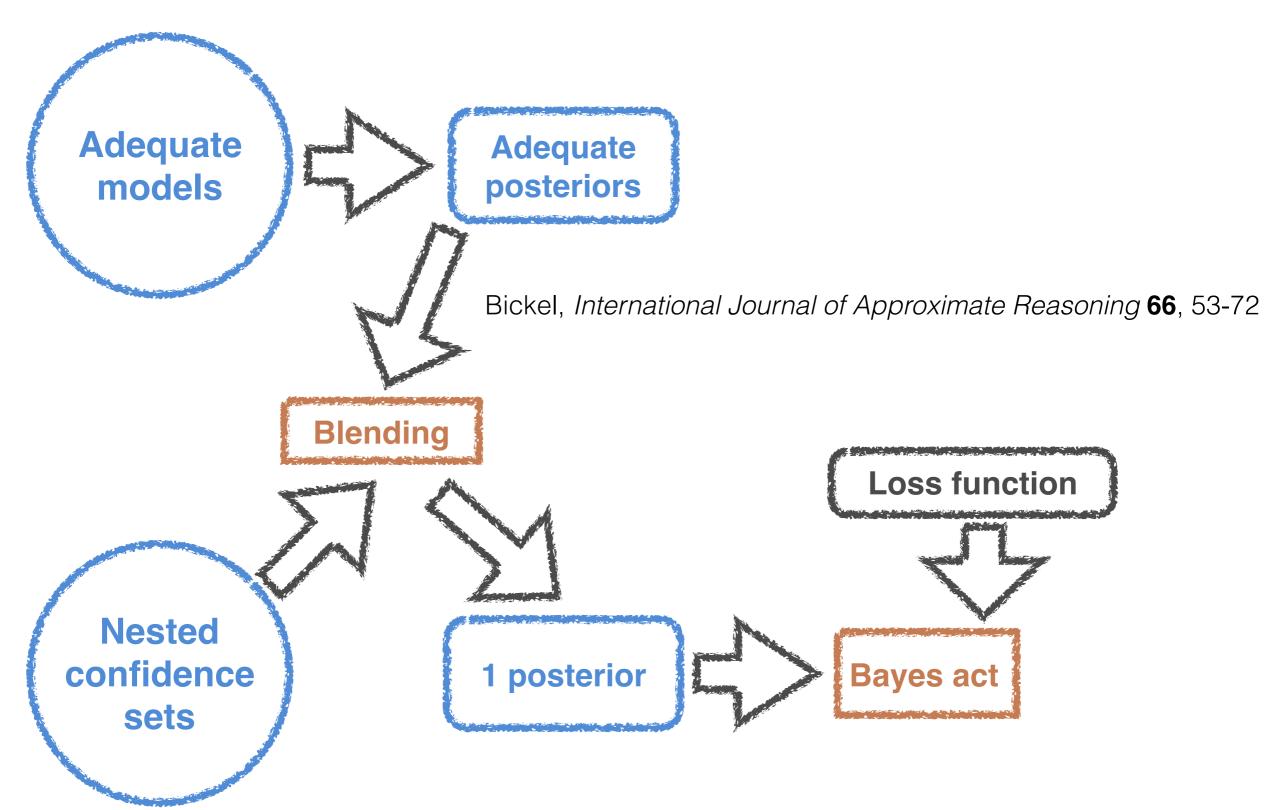
Loss function

$$\delta\left(a,\kappa\right) = \arg\inf_{\delta\in\mathcal{D}} \left(\kappa \sup_{M\in\mathcal{M}(a)} E_M\left(\ell\left(\vartheta,\delta\right)\right) + (1-\kappa) \inf_{M\in\mathcal{M}(a)} E_M\left(\ell\left(\vartheta,\delta\right)\right)\right)$$

Decisions under robust Bayes rules applied to models of sufficient evidence



Decisions under the entropy-maximizing model of sufficient evidence



Posterior distributions of the parameter

• Set \dot{P} of adequate posterior distributions on (Θ, A)

• Subjective interpretation: interval levels of belief

• Objective interpretation: physical constraints

• Set $\ddot{\mathcal{P}}$ of confidence distributions

 \circ Confidence distribution \ddot{P} on (Θ, \mathcal{A})

Information theory

• Information divergence of P with respect to Q on (Θ, A) :

$$P \ll Q \implies I(P||Q) = \int dP \log\left(\frac{dP}{dQ}\right)$$

 $P \not\ll Q \implies I(P||Q) = \infty$

• Inferential gain of Q relative to \ddot{P} given \dot{P} :

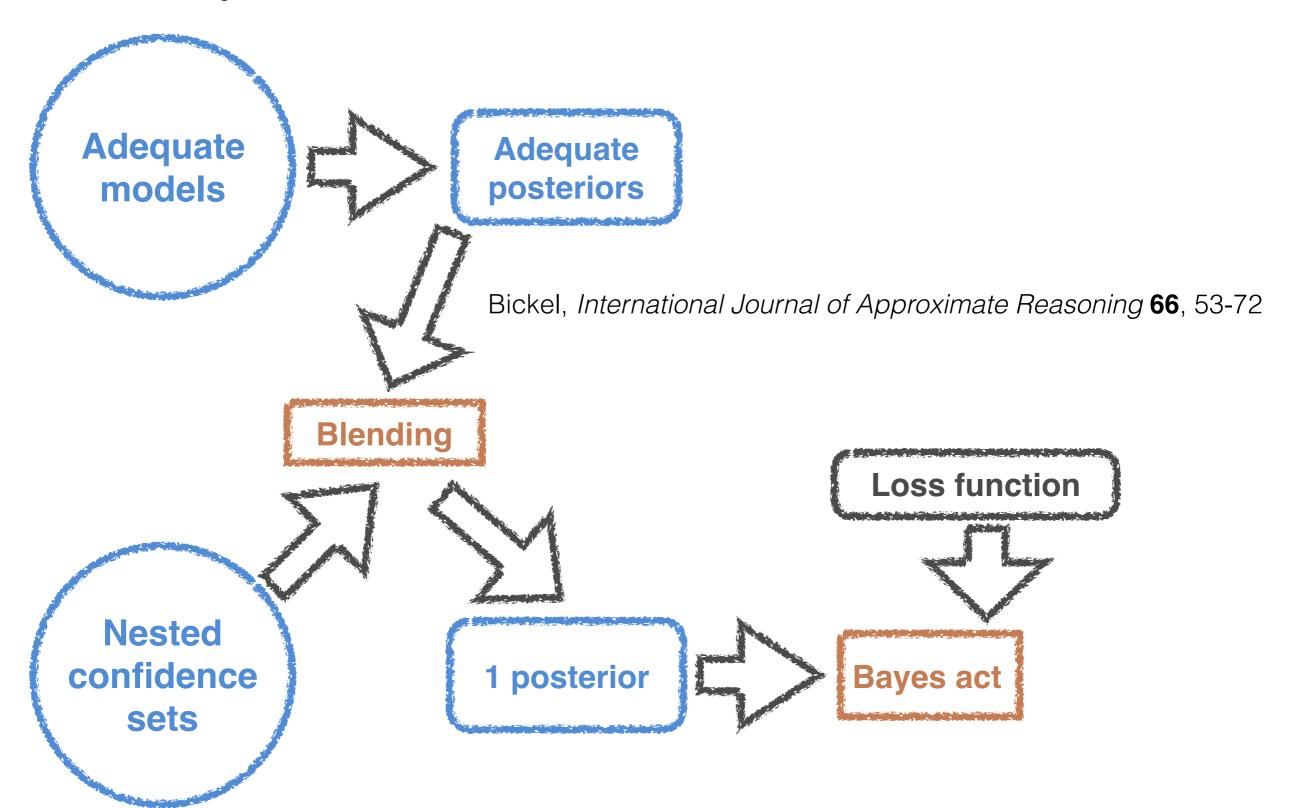
$$I\left(\dot{P}||\ddot{P}\leadsto Q\right) = I\left(\dot{P}||\ddot{P}\right) - I\left(\dot{P}||Q\right)$$

• Subset $\dot{P}(\ddot{P}) = \{\dot{P} \in \dot{P} : I(\dot{P}||\ddot{P}) < \infty\}$ of Bayes posteriors

Game theory

- The inferential gain of Q is $I\left(\dot{P}||\ddot{P}\leadsto Q\right)=I\left(\dot{P}||\ddot{P}\right)-I\left(\dot{P}||Q\right)$.
- The <u>blended posterior distribution</u> \hat{P} is defined by this game: $\inf_{\dot{P} \in \dot{P}(\ddot{P})} I\left(\dot{P}||\ddot{P} \leadsto \hat{P}\right) = \sup_{Q \in \mathcal{P}} \inf_{\dot{P} \in \dot{P}(\ddot{P})} I\left(\dot{P}||\ddot{P} \leadsto Q\right).$
- If $I\left(\dot{P}||\ddot{P}\right) < \infty$ for some $\dot{P} \in \dot{P}$ and if $\dot{P}\left(\ddot{P}\right)$ is convex, then $I\left(\hat{P}||\ddot{P}\right) = \inf_{\dot{P} \in \dot{P}\left(\ddot{P}\right)} I\left(\dot{P}||\ddot{P}\right)$.
 - F. Topsøe, Kybernetika 15 (1979), 8-27; P. Harremoës and F. Topsøe, Entropy 3 (2001), 191-226; F. Topsøe, in Entropy, Search, Complexity (Springer, 2007), 179-207

Decisions under the entropy-maximizing Bayesian model of sufficient evidence

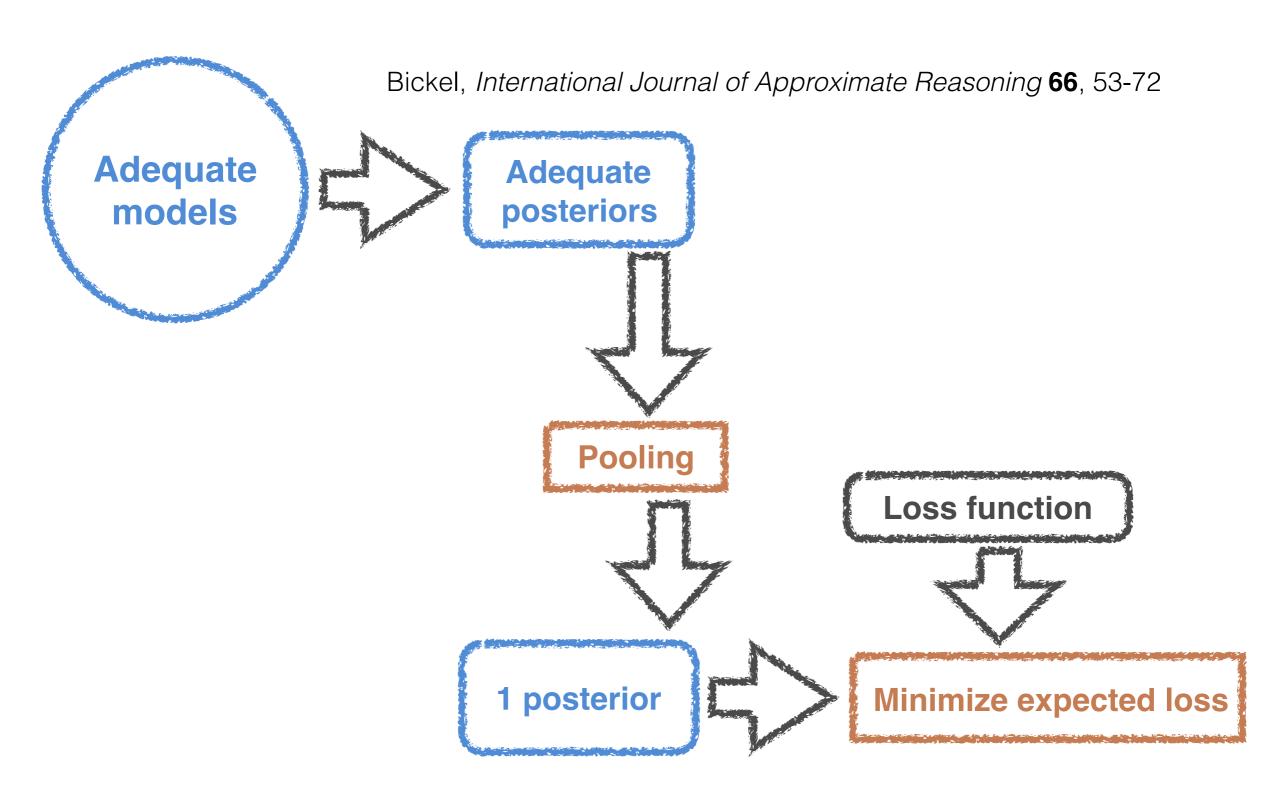


Pooling methods

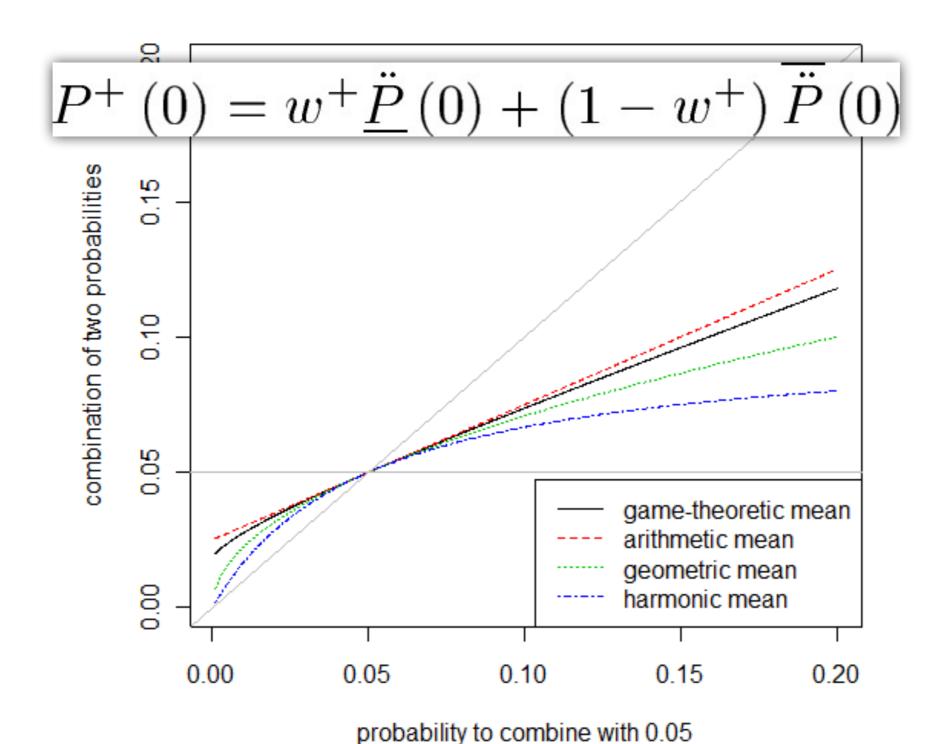
- Good derived a harmonic mean of p-values from Bayes' rule
- Examples of subjectively weighting each expert's distribution:
 - Minimizing a weighted sum of divergences from the distributions being combined yields a linear combination of the distributions
 - Any linearly combined marginal distribution is the same whether marginalization or combination is carried out first
 - Weighted multiplicative combination of the distributions
 - Externally Bayesian updating



Decisions under minimax-redundancy pooling of models of small codelengths



Conflicting probabilities





The three players

- Combiner is you, the statistician who combines the candidate distributions
 - Goal 1: minimize error; Goal 2: beat Chooser
- Chooser is the imaginary statistician who instead chooses a single candidate distribution
 - Goal 1: minimize error; Goal 2: beat Combiner
- Nature picks the true distribution among those that are plausible in order to help Chooser







Information game

Information divergence and inferential gain:

$$D(P||Q) = \int dP(\xi) \log \frac{dP(\xi)}{dQ(\xi)}$$
$$D(P'||P'' \to Q) = D(P'||P'') - D(P'||Q)$$

• Utility paid to Statistician 2 (Combiner or Chooser):

$$U\left(\dot{P}, P_1, P_2\right) = \left(-D\left(\dot{P}||P_2\right), D\left(\dot{P}||P_1 \to P_2\right)\right)$$

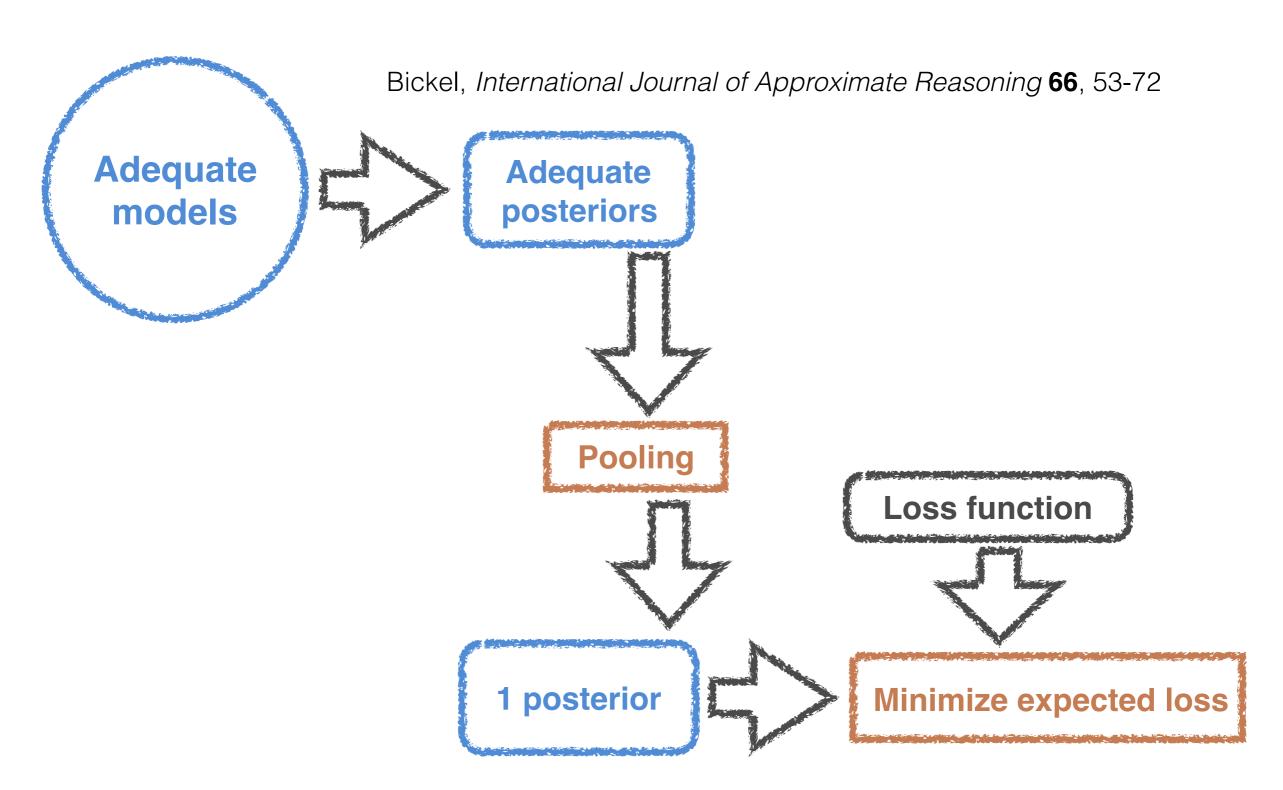
Reduction to game of Combiner v. Nature-Chooser Coalition:

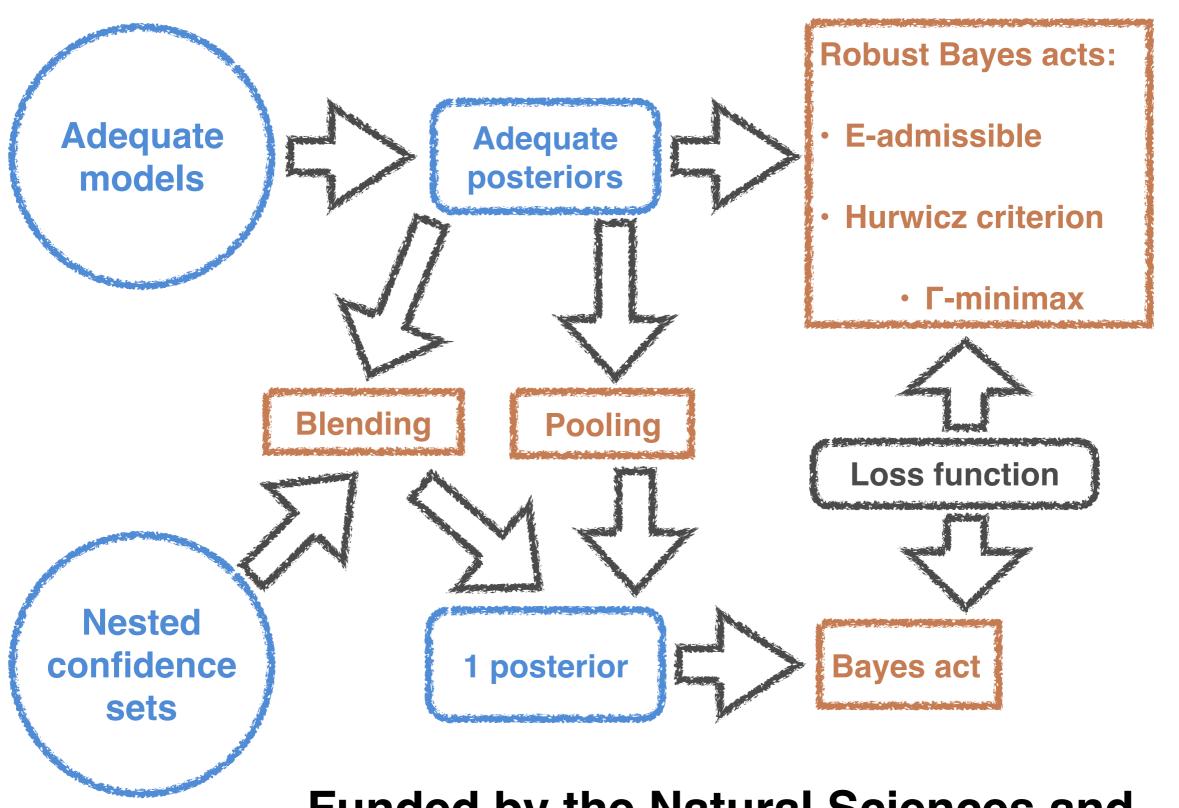
$$P^{+} = \arg\inf_{Q} \sup_{P'} D\left(P'||Q\right)$$





Decisions under minimax-redundancy pooling of models of small codelengths





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